

Cockcroft Theory Lectures

Solving the wave equation equation in cylindrical and spherical coordinate systems.

Bessel's functions and Spherical Harmonics

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SECTION 1

Coordinate systems and the Laplacian

- Why ∇ is different in different coordinate systems.
- Plane polar coordinates: Grad, Div and the Laplacian.
- Cylindrical polar coordinates: Grad, Div, Curl and the Laplacian.
- Spherical polar coordinates: Grad, Div, Curl and the Laplacian. (Lecture 3)

Grad, Div and Laplacian

- Recall what grad, div and Laplacian are in two dimensions.

$$\nabla\psi = \frac{\partial\psi}{\partial x}\underline{i} + \frac{\partial\psi}{\partial y}\underline{j}, \quad \nabla \cdot (v_1\underline{i} + v_2\underline{j}) = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} \quad \text{and} \quad \Delta\psi = \nabla \cdot \nabla\psi$$

- Grad, div and Laplacian are all linear with respect to addition and multiplication by a scalar constant λ . (Show)

$$\nabla(\psi_1 + \psi_2) = \nabla\psi_1 + \nabla\psi_2, \quad \nabla \cdot (\underline{v}_1 + \underline{v}_2) = \nabla \cdot \underline{v}_1 + \nabla \cdot \underline{v}_2,$$

$$\Delta(\psi_1 + \psi_2) = \Delta\psi_1 + \Delta\psi_2$$

$$\nabla(\lambda\psi) = \lambda\nabla\psi, \quad \nabla \cdot (\lambda\underline{v}) = \lambda\nabla \cdot \underline{v} \quad \text{and} \quad \Delta(\lambda\psi) = \lambda\Delta\psi$$

- However the effect of multiplication by a scalar field, then we must use the appropriate product rule. (Show)

$$\nabla(f\psi) = f\nabla\psi + \psi\nabla f \quad \text{and} \quad \nabla \cdot (f\underline{v}) = f\nabla \cdot \underline{v} + (\nabla f) \cdot \underline{v}$$

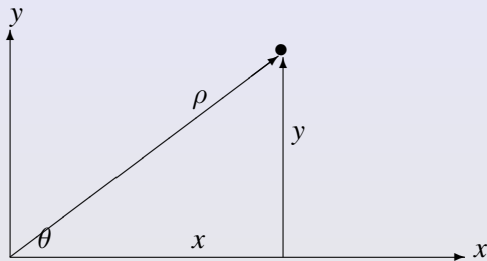
- We also have the function of a function rule. For example if ψ and \underline{v} are functions of two scalar fields f and g then (Show)

$$\nabla(\psi(f, g)) = \frac{\partial\psi}{\partial f}\nabla f + \frac{\partial\psi}{\partial g}\nabla g \quad \text{and} \quad \nabla \cdot (\underline{v}(f, g)) = \frac{\partial v}{\partial f} \cdot \nabla f + \frac{\partial v}{\partial g} \cdot \nabla g$$

Plane polar coordinates

- Plane polar coordinates are given by the pair (ρ, θ) where $\rho \in \mathbb{R}$, $\rho \geq 0$ and $\theta \in \mathbb{R}$, $0 \leq \theta < 2\pi$.
- The relationship between (ρ, θ) and Cartesian coordinates is given by

$$x = \rho \cos \theta \quad \text{and} \quad y = \rho \sin \theta$$



- These can be inverted

$$\rho = \sqrt{x^2 + y^2} \quad \text{and} \quad \theta = \arctan(y/x)$$

where we need to make sure θ is in the correct quadrant.

Scalar and vector fields

- Since we have two coordinate systems, we can represent a scalar field in two different ways.
- Let $\psi = \psi(x, y)$ be a real scalar field. There is an associated scalar field $\hat{\psi} = \hat{\psi}(\rho, \theta)$, which is defined by

$$\hat{\psi}(\rho, \theta) = \psi(\rho \cos \theta, \rho \sin \theta) = \psi(x, y)$$

- Using the chain rule we have

$$\frac{\partial \hat{\psi}}{\partial \rho} = \frac{\partial x}{\partial \rho} \frac{\partial \psi}{\partial x} + \frac{\partial y}{\partial \rho} \frac{\partial \psi}{\partial y} = \cos \theta \frac{\partial \psi}{\partial x} + \sin \theta \frac{\partial \psi}{\partial y}$$

and

$$\frac{\partial \hat{\psi}}{\partial \theta} = \frac{\partial \psi}{\partial x} \frac{\partial x}{\partial \theta} + \frac{\partial \psi}{\partial y} \frac{\partial y}{\partial \theta} = \rho \sin \theta \frac{\partial \psi}{\partial x} - \rho \cos \theta \frac{\partial \psi}{\partial y}$$

- Since the coordinates (x, y) and (ρ, θ) “represent the same point” but in different coordinate systems, people tend to write $\psi = \hat{\psi}$.
- Likewise for vector fields we write $\underline{v}(\rho, \theta) = \underline{v}(x, y)$.

Plane polar coordinates: Orthonormal basis

- Given a scalar field $\psi = \psi(\rho, \theta)$ then

$$\nabla\psi = \frac{\partial\psi}{\partial\rho}\nabla\rho + \frac{\partial\psi}{\partial\theta}\nabla\theta$$

- There are two important vector fields $\underline{e}_\rho = \underline{e}_\rho(\rho, \theta)$ and $\underline{e}_\theta = \underline{e}_\theta(\rho, \theta)$ defined by

$$\underline{e}_\rho = \frac{\nabla\rho}{\|\nabla\rho\|} \quad \text{and} \quad \underline{e}_\theta = \frac{\nabla\theta}{\|\nabla\theta\|}$$

- We can show that (Show)

$$\underline{e}_\rho = \cos\theta\underline{i} + \sin\theta\underline{j} \quad \text{and} \quad \underline{e}_\theta = -\sin\theta\underline{i} + \cos\theta\underline{j}$$

- Furthermore (Show)

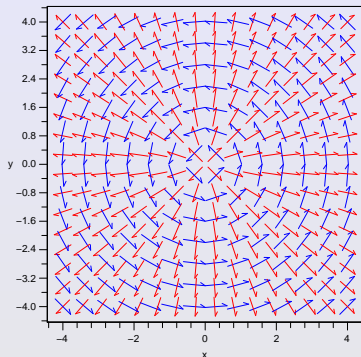
$$\nabla\rho = \underline{e}_\rho \quad \text{and} \quad \nabla\theta = \frac{1}{\rho}\underline{e}_\theta$$

- Hence

$$\nabla\psi = \frac{\partial\psi}{\partial\rho}\underline{e}_\rho + \frac{\partial\psi}{\partial\theta}\frac{1}{\rho}\underline{e}_\theta$$

Plane polar coordinates: Orthonormal basis

$$\underline{e}_\rho = \cos \theta \underline{i} + \sin \theta \underline{j} \quad \text{and} \quad \underline{e}_\theta = -\sin \theta \underline{i} + \cos \theta \underline{j}$$



\underline{e}_ρ is red
 \underline{e}_θ is blue

- Observe that \underline{e}_ρ and \underline{e}_θ depend on the position.
- Observe that \underline{e}_ρ and \underline{e}_θ are orthonormal, that is $\underline{e}_\rho \cdot \underline{e}_\theta = 0$ and $\underline{e}_\rho \cdot \underline{e}_\rho = \underline{e}_\theta \cdot \underline{e}_\theta = 1$. Thus we have an orthonormal vector field basis.

Plane polar coordinates: Div

- From the function of a function rule the divergence of a vector field $\underline{v}(\rho, \theta) = v_\rho \underline{e}_\rho + v_\theta \underline{e}_\theta$ is given by (Why?)

$$\nabla \cdot \underline{v} = v_\rho \nabla \cdot \underline{e}_\rho + \nabla v_\rho \cdot \underline{e}_\rho + v_\theta \nabla \cdot \underline{e}_\theta + \nabla v_\theta \cdot \underline{e}_\theta$$

- Now

$$\nabla v_\rho = \frac{\partial v_\rho}{\partial \rho} \underline{e}_\rho + \frac{1}{\rho} \frac{\partial v_\rho}{\partial \theta} \underline{e}_\theta \quad \text{and} \quad \nabla v_\theta = \frac{\partial v_\theta}{\partial \rho} \underline{e}_\rho + \frac{1}{\rho} \frac{\partial v_\theta}{\partial \theta} \underline{e}_\theta$$

- and (Show)

$$\nabla \cdot \underline{e}_\rho = \frac{1}{\rho} \quad \text{and} \quad \nabla \cdot \underline{e}_\theta = 0$$

hence

$$\begin{aligned} \nabla \cdot \underline{v} &= \frac{v_\rho}{\rho} + \frac{\partial v_\rho}{\partial \rho} + \frac{1}{\rho} \frac{\partial v_\theta}{\partial \theta} \\ \nabla \cdot \underline{v} &= \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho v_\rho) + \frac{1}{\rho} \frac{\partial v_\theta}{\partial \theta} \end{aligned}$$

Plane polar coordinates: Laplacian



$$\nabla\psi = \frac{\partial\psi}{\partial\rho}\mathbf{e}_\rho + \frac{1}{\rho}\frac{\partial\psi}{\partial\theta}\mathbf{e}_\theta$$

and

$$\nabla \cdot \underline{v} = \frac{1}{\rho} \frac{\partial}{\partial\rho} (\rho v_\rho) + \frac{1}{\rho} \frac{\partial v_\theta}{\partial\theta}$$

- Hence (Show)

$$\Delta\psi = \frac{1}{\rho} \frac{\partial}{\partial\rho} \left(\rho \frac{\partial\psi}{\partial\rho} \right) + \frac{1}{\rho^2} \frac{\partial^2\psi}{\partial\theta^2}$$

Cylindrical Coordinates: Grad, Div and Laplacian

- Cylindrical Coordinates are given by (ρ, θ, z) where

$$\rho \geq 0, \quad 0 \leq \theta < 2\pi \quad \text{and} \quad -\infty < z < \infty$$

- The relationship with Cartesian coordinates (x, y, z) is given by

$$x = \rho \cos \theta, \quad y = \rho \sin \theta \quad \text{and} \quad z = z$$

The orthogonal vector basis is given by

$$\underline{e}_\rho = \frac{\nabla \rho}{\|\nabla \rho\|}, \quad \underline{e}_\theta = \frac{\nabla \theta}{\|\nabla \theta\|} \quad \text{and} \quad \underline{e}_z = \frac{\nabla z}{\|\nabla z\|}$$

- Giving

$$\underline{e}_\rho = \cos \theta \underline{i} + \sin \theta \underline{j}, \quad \underline{e}_\theta = -\sin \theta \underline{i} + \cos \theta \underline{j} \quad \text{and} \quad \underline{e}_z = \underline{k}$$

Cylindrical Coordinates: Grad, Div and Laplacian

- Let $\psi = \psi(\rho, \theta, z)$ and $\underline{v} = v_\rho \underline{e}_\rho + v_\theta \underline{e}_\theta + v_z \underline{e}_z$, where $v_\rho = v_\rho(\rho, \theta, z)$ etc.
- The Grad, Div and Laplacian are given by

$$\nabla \psi = \frac{\partial \psi}{\partial \rho} \underline{e}_\rho + \frac{1}{\rho} \frac{\partial \psi}{\partial \theta} \underline{e}_\theta + \frac{\partial \psi}{\partial z} \underline{e}_z$$

$$\nabla \cdot \underline{v} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho v_\rho) + \frac{1}{\rho} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z}$$

$$\Delta \psi = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \psi}{\partial \theta^2} + \frac{\partial^2 \psi}{\partial z^2}$$

- The curl is given by

$$\nabla \times \underline{v} = \left(\frac{1}{\rho} \frac{\partial v_z}{\partial \theta} - \frac{\partial v_\theta}{\partial z} \right) \underline{e}_\rho + \left(\frac{\partial v_\rho}{\partial z} - \frac{\partial v_z}{\partial \rho} \right) \underline{e}_\theta + \frac{1}{\rho} \left(\frac{\partial(\rho v_\theta)}{\partial \rho} - \frac{\partial v_\rho}{\partial \theta} \right) \underline{e}_z$$

SECTION 2

Wave Equation on the disc and Bessel's functions

- The disc wave equation.
- Separation of variables and the time equation.
- Disc harmonics and Bessel's functions.
- Eigen properties of disc harmonics.
- Orthogonality properties of disc harmonics.
- Scalar waves in cylindrical wave guides.

Wave on the disc

- The wave equation on the disc for the scalar $\psi = \psi(t, \rho, \theta)$ is given by

$$\frac{\partial^2 \psi}{\partial t^2} - \Delta_{\text{disc}} \psi = 0$$

where the Laplace operator in plane polar coordinates is

$$\Delta_{\text{disc}} \psi = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \psi}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \psi}{\partial \theta^2}$$

- We use separation of variables $\psi(t, \rho, \theta) = T(t)\mathcal{J}(\rho, \theta)$ to give (show)

$$\frac{d^2 T}{dt^2} + \omega^2 T = 0 \quad \text{and} \quad \Delta_{\text{disc}} \mathcal{J}(\rho, \theta) + \omega^2 \mathcal{J} = 0$$

- Clearly we can solve the T equation by setting

$$T(t) = e^{i\omega t} \quad \text{and} \quad e^{-i\omega t}$$

where $\omega > 0$.

Separation of the disc Laplace operator.

- We are left with looking at the eigenvalues and eigenfunctions of the disc Laplace operator

$$\Delta_{\text{disc}} \mathcal{J} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \mathcal{J}}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \mathcal{J}}{\partial \theta^2} = -\omega^2 \mathcal{J}$$

where $\mathcal{J} = \mathcal{J}(\rho, \theta)$

- This we solve by separation of variables, Setting

$$\mathcal{J}(\rho, \theta) = \mathbb{P}(\rho)\Theta(\theta)$$

- Using $-m^2$ as the constant of separation gives (Show)

$$\begin{aligned} \frac{d^2 \Theta}{d\theta^2} + m^2 \Theta &= 0 \\ \rho \frac{d}{d\rho} \left(\rho \frac{d\mathbb{P}}{d\rho} \right) + (\omega^2 \rho^2 - m^2) \mathbb{P} &= 0 \end{aligned}$$

Separation of the disc Laplace operator, The Θ equation.

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$$\frac{d^2\Theta}{d\theta^2} + m^2\Theta = 0$$

- The Θ equation is solved by setting

$$\Theta(\theta) = \Theta_m(\theta) = A_m e^{im\theta}$$

- Since θ is an angle so that $\Theta(\theta + 2\pi) = \Theta(\theta)$ thus $m \in \mathbb{Z}$.
- For real solution it is necessary to set

$$\Theta_m = \begin{cases} A_m \cos(m\theta) + B_m \sin(m\theta) & \text{if } m > 0 \\ A_0 & \text{if } m = 0 \end{cases}$$

Separation of the disc Laplace operator, The P equation.

$$\rho \frac{d}{d\rho} \left(\rho \frac{dP}{d\rho} \right) + (\omega^2 \rho^2 - m^2)P = 0$$

- We transform the P equation into the **Bessel's** equation by setting

$$\rho = \frac{x}{\omega} \quad \text{and} \quad P(\rho) = y(x)$$

- Thus

$$\frac{d}{d\rho} = \omega \frac{d}{dx}$$

Giving

$$x \frac{d}{dx} \left(x \frac{dy}{dx} \right) + (x^2 - m^2)y = 0$$

where $y = y(x)$ and $m \in \mathbb{Z}$.

- This is **Bessel's equation** of order m .

Bessel functions

- We have obtained Bessel's equation, $y = y(x)$ and $m \in \mathbb{Z}$.

$$x \frac{d}{dx} \left(x \frac{dy}{dx} \right) + (x^2 - m^2)y = 0$$

- These are solved by Bessel functions.
- Bessel's equation is a second order ordinary differential equation. Therefore we know the answer consists of two independent solutions.

$$y(x) = AJ_m(x) + BY_m(x)$$

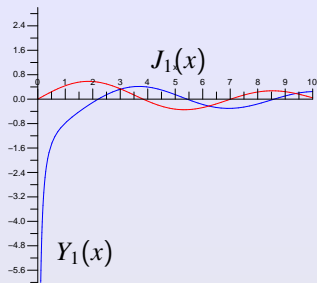
where we call $J_m(x)$ a **Bessel function of the first kind** and $Y_m(x)$ a **Bessel function of the second kind**.

Bessel functions

- In the limit $x \rightarrow 0$,

$$\lim_{x \rightarrow 0} J_m(x) = J_m(0) \quad \text{is a finite quantity}$$

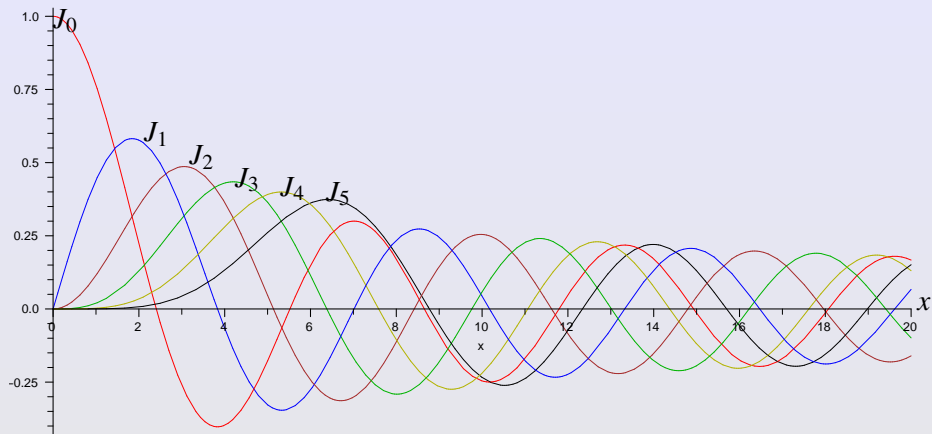
$$\lim_{x \rightarrow 0} Y_m(x) = \infty$$



- Since $x = 0$ corresponds to $\rho = 0$ is the centre of the disc, we require that the coefficient of $Y_m(x)$ is zero.
- Thus $y(x) = AJ_m(x)$.
- After a long calculation we can show that

$$J_m(x) = \sum_{s=0}^{\infty} \frac{(-1)^s x^{m+2s}}{2^{m+2s} s! (m+s)!}$$

Plotting the first 6 Bessel functions (of the first kind) gives.



Observe that each Bessel function has an infinite set of roots (zeros).

Recap the wave equation on the disc

- For fixed frequency ω

$$\Delta_{\text{disc}} \mathcal{J} = \frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial \mathcal{J}}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 \mathcal{J}}{\partial \theta^2} = -\omega^2 \mathcal{J}$$

- Since we can superimpose solutions the general solution is given by

$$\mathcal{J}(\rho, \theta) = \sum_{m=-\infty}^{\infty} A_m e^{im\theta} J_m(\omega\rho)$$

- Thus the solution to the wave equation $\frac{\partial \psi}{\partial t^2} + \Delta_{\text{disc}} \psi = 0$ is a sum of solutions of the form

$$\psi(t, \rho, \theta) = e^{i\omega t} e^{im\theta} J_m(\omega\rho) \quad \text{and} \quad \psi(t, \rho, \theta) = e^{-i\omega t} e^{im\theta} J_m(\omega\rho)$$

where $m \in \mathbb{Z}$ and $\omega > 0$.

- To establish the possible values of ω we need the boundary conditions.

Boundary conditions

- Let us consider a cylinder of radius R . We impose boundary conditions that $\psi = 0$ when $\rho = R$. That is

$$\psi(t, R, \theta) = 0 \quad \text{for all } t, \theta$$

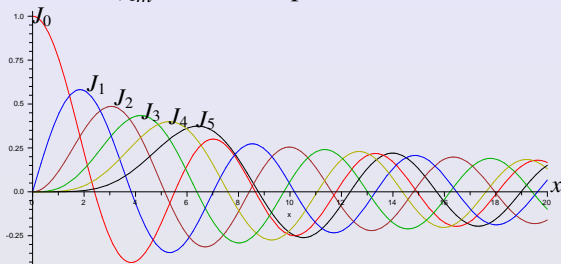
- Thus for each $m \in \mathbb{Z}$, $m \geq 0$ we have $J_m(\omega R) = 0$
- Thus the solution to the wave equation $\frac{\partial \psi}{\partial t^2} + \Delta_{\text{disc}} \psi = 0$ is a sum of solutions of the form

$$\psi(t, \rho, \theta) = e^{i\omega t} e^{im\theta} J_m(\omega \rho) \quad \text{where} \quad J_m(\omega R) = 0$$

- Therefore we need to know the zeros (roots) of the Bessel functions.
- If χ_m^s is a root of the Bessel function, i.e. $J_m(\chi_m^s) = 0$ then $\omega = \frac{\chi_m^s}{R}$ is a permitted value of ω .

Roots of Bessel functions

- Enumerate all the roots of J_m . That is let χ_m^s be the s 'th root of J_m so that
$$J_m(\chi_m^s) = 0$$
- Since for $m > 0$, $J_m(0) = 0$, we set $\chi_m^0 = 0$.
- Thus in all cases we let χ_m^1 be the first positive root of J_m .



	χ_m^0	χ_m^1	χ_m^2	χ_m^3	χ_m^4	χ_m^5	χ_m^6	χ_m^7
J_0	—	2.40	5.52	8.65	11.79	14.93	18.07	21.21
J_1	0.	3.83	7.01	10.17	13.32	16.47	19.62	22.76
J_2	0.	5.13	8.41	11.62	14.80	17.96	21.12	24.27
J_3	0.	6.38	9.76	13.02	16.22	19.41	22.58	25.75
J_4	0.	7.58	11.06	14.37	17.62	20.83	24.02	27.20
J_5	0.	8.77	12.34	15.70	18.98	22.22	25.43	28.63

Complete solution to the wave equation on the disc

- Thus the complete solution to the wave equation for $\psi = \psi(t, \rho, \theta)$

$$\frac{\partial \psi}{\partial t^2} + \Delta_{\text{disc}} \psi = 0 \quad \text{with boundary conditions} \quad \psi(t, R, \theta) = 0$$

is given by

$$\psi(t, \rho, \theta) = \sum_{s=1}^{\infty} \sum_{m=-\infty}^{\infty} \left(A_{ms} \exp\left(\frac{i\chi_m^s t}{R} + im\theta\right) J_m\left(\frac{\chi_m^s \rho}{R}\right) + B_{ms} \exp\left(\frac{-i\chi_m^s t}{R} + im\theta\right) J_m\left(\frac{\chi_m^s \rho}{R}\right) \right)$$

- The values of A_{ms}, B_{ms} are determined by the initial conditions, via the use of the inner product.
- It is also possible to write the general solution in terms of cos and sin, so as to guarantee ψ is real.

Eigen properties of the disc harmonics

- The set of solutions to the (ρ, θ) part of the wave equation i.e. $\Delta_{\text{disc}} \mathcal{J} = -\omega^2 \mathcal{J}$ subject to the boundary condition $\mathcal{J}(R, \theta) = 0$ are called **disc harmonics**.
- They are defined for each $m \in \mathbb{Z}$ and $s = 1, 2, \dots$ I.e. we set

$$\mathcal{J}_m^s(\rho, \theta) = e^{im\theta} J_m\left(\frac{\chi_m^s \rho}{R}\right)$$

- The disc harmonics are eigenfunctions of Δ_{disc} and the operator $\frac{\partial^2}{\partial^2 \theta}$, with eigenvalues $-\left(\frac{\chi_m^s}{R}\right)^2$ and $-m^2$ respectively
- i.e.

$$\Delta_{\text{disc}} \mathcal{J}_m^s = -\left(\frac{\chi_m^s}{R}\right)^2 \mathcal{J}_m^s \quad \text{and} \quad \frac{\partial^2}{\partial \theta^2} \mathcal{J}_m^s = -m^2 \mathcal{J}_m^s$$

Inner product and initial conditions

- There is an inner product for functions on the disk given by

$$\langle f, g \rangle = \int_{\rho=0}^R \int_{\theta=0}^{2\pi} \rho f(\rho, \theta) g(\rho, \theta) d\theta d\rho$$

- Again the disc harmonics are orthogonal i.e.

$$\langle \mathcal{J}_m^s, \mathcal{J}_{m'}^{s'} \rangle = 0$$

If $m \neq m'$ or $n \neq n'$.

- However the disc harmonics are not normalised and

$$\langle \mathcal{J}_m^s, \mathcal{J}_m^s \rangle = \frac{\pi R^2}{2} \left(\frac{dJ_m}{d\rho}(\chi_m^s) \right)^2$$

- We use this inner product to calculate the coefficient A_{ms}, B_{ms} in terms of the initial positions and velocities of the disc.

Cylindrical wave guides

- Let us solve the equation for $\psi(t, \rho, \theta, z)$

$$\frac{\partial^2 \psi}{\partial t^2} - \Delta \psi = 0$$

subject to the boundary conditions

$$\psi(t, R, \theta, z) = 0 \quad \text{and} \quad \psi(t, 0, \theta, z) \text{ is bounded}$$

- By separation of variables $\psi(t, \rho, \theta) = T(t)\Upsilon(\rho, \theta)Z(z)$ we have

$$\frac{d^2 T}{dt^2} = -\omega^2 T, \quad \Delta_{\text{disc}} \Upsilon = -k^2 \Upsilon \quad \text{and} \quad \frac{d^2 Z}{dz^2} = \epsilon \mu^2 Z$$

with

$$k = \pm \chi_m^s / R, \quad \epsilon = \pm 1 \quad \text{and} \quad \omega^2 = k^2 - \epsilon \mu^2$$

- The sign of ϵ determines if the wave are propagating or non propagating.
 - If $\epsilon = 1$ the the waves are non propagating.
 - If $\epsilon = -1$ the the waves are propagating

Non propagating waves

- If $\epsilon = 1$ then

$$\frac{d^2 Z}{dz^2} = \mu^2 Z \quad \text{implies} \quad Z(z) = e^{\pm \mu z}$$

- We consider a semi infinite cylinder. I.e. $z > 0$.
- On “physical” grounds we exclude the solution $Z(z) \rightarrow \infty$ as $z \rightarrow \infty$. Thus we have $Z(z) = e^{-\mu z}$.
- This is a non propagating since $\psi \rightarrow 0$ exponentially as $z \rightarrow \infty$.

Propagating waves

- If $\epsilon = -1$ then

$$\frac{d^2 Z}{dz^2} = -\mu^2 Z \quad \text{implies} \quad Z(z) = e^{\pm i\mu z} \quad \text{and} \quad \omega^2 = k^2 + \mu^2 = (\chi^s/R)^2 + \mu^2$$

- Again we consider a semi infinite cylinder. I.e. $z > 0$.
- $Z(z)$ remains order 1 as $z \rightarrow \infty$. So these are propagating waves.
- Solutions to the wave equation take the form

$$\psi(t, \rho, \theta) = e^{\pm i\omega t \pm i\mu z + im\theta} J_m\left(\frac{\chi_m^s \rho}{R}\right)$$

- Observe that

$$|\omega| \geq \chi^s/R \geq \chi_0^1/R \approx 2.4/R$$

Thus there is a minimum frequency for propagating modes.

- The speed of propagations is given by

$$\frac{|\mu|}{|\omega|} = \frac{\sqrt{\omega^2 - k^2}}{|\omega|} = \sqrt{1 - \frac{k^2}{\omega^2}} < 1$$

Thus waves slow down in a cylinder. Without a cylinder $\frac{|\mu|}{|\omega|} = 1$.

SECTION 3

Wave Equation on the sphere and Spherical Harmonics

- The Laplace operator in spherical coordinates.
- The spherical wave equation.
- Separation of variables and the time equation.
- The spherical equation.
- The associated Legendre equation
- Eigen properties of spherical harmonics
- Orthogonality properties of spherical harmonics
- Laplace's equation and monopoles and dipoles.

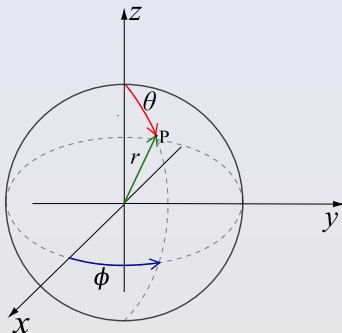
Spherical Coordinates: Grad, Div and Laplacian

- Spherical Coordinates are given by (r, θ, ϕ) where

$$r \geq 0, \quad 0 \leq \theta \leq \pi \quad \text{and} \quad 0 \leq \phi \leq 2\pi$$

- The relationship with Cartesian coordinates (x, y, z) is given by

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi \quad \text{and} \quad z = r \cos \theta$$



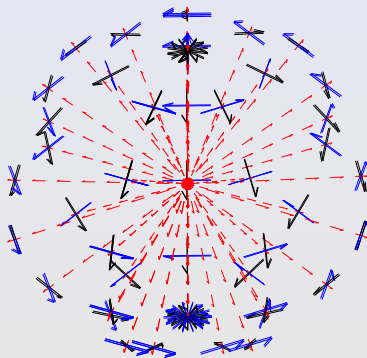
Spherical Coordinates

The orthogonal vector basis is given by

$$\underline{e}_r = \frac{\nabla r}{\|\nabla r\|}, \quad \underline{e}_\theta = \frac{\nabla \theta}{\|\nabla \theta\|} \quad \text{and} \quad \underline{e}_\phi = \frac{\nabla \phi}{\|\nabla \phi\|}$$

Hence

$$\begin{aligned}\underline{e}_r &= \sin \theta \cos \phi \underline{i} + \sin \theta \sin \phi \underline{j} + \cos \theta \underline{k}, \\ \underline{e}_\theta &= \cos \theta \cos \phi \underline{i} + \cos \theta \sin \phi \underline{j} + \sin \theta \underline{k} \quad \text{and} \\ \underline{e}_\phi &= -\sin \phi \underline{i} + \cos \phi \underline{j}\end{aligned}$$



\underline{e}_r are red
 \underline{e}_ϕ are blue
 \underline{e}_θ are black

Spherical Coordinates: Grad, Div and Laplacian

- Let $\psi = \psi(r, \theta, z)$ and $\underline{v} = v_r \underline{e}_r + v_\theta \underline{e}_\theta + v_z \underline{e}_z$, where $v_r = v_r(r, \theta, z)$ etc.
- The Grad, Div and Laplacian are given by

$$\nabla \psi = \frac{\partial \psi}{\partial r} \underline{e}_r + \frac{1}{r} \frac{\partial \psi}{\partial \theta} \underline{e}_\theta + \frac{1}{r \sin \theta} \frac{\partial \psi}{\partial \phi} \underline{e}_z$$

$$\nabla \cdot \underline{v} = \frac{1}{r} \frac{\partial}{\partial r^2} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

$$\Delta \psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \psi}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 \psi}{\partial \phi^2}$$

- The curl is given by

$$\begin{aligned} \nabla \times \underline{v} = & \frac{1}{r \sin \theta} \left(\frac{\partial \sin \theta v_\phi}{\partial \theta} - \frac{\partial v_\theta}{\partial \phi} \right) \underline{e}_r + \left(\frac{1}{r \sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{1}{r} \frac{\partial}{\partial r} (r v_\phi) \right) \underline{e}_\theta \\ & + \frac{1}{r} \left(\frac{\partial (r v_\theta)}{\partial r} - \frac{\partial v_r}{\partial \theta} \right) \underline{e}_\phi \end{aligned}$$

The Laplace operator in spherical coordinates.

- Recall the Laplace operator in spherical coordinates.

$$\Delta\psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial\psi}{\partial\theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2\psi}{\partial\phi^2}$$

- We can rewrite this as

$$\Delta\psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2} \Delta_{\text{sph}}\psi$$

where

$$\Delta_{\text{sph}}\psi = \frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial\psi}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2\psi}{\partial\phi^2}$$

is the Laplace operator on the sphere.

- Laplace's equation:

$$\Delta\psi = 0 \quad \text{for} \quad \psi = \psi(r, \theta, \phi)$$

Ψ could be the gravitational potential or electrostatic potential for space with a single source at the origin $r = 0$.

We shall solve this later.

The spherical wave equation.

- First we shall solve the spherical wave equation

$$\frac{\partial^2 \psi}{\partial t^2} - \Delta_{\text{sph}} \psi = 0 \quad \text{for} \quad \psi = \psi(t, \theta, \phi)$$

where

$$\Delta_{\text{sph}} \psi = \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \psi}{\partial \phi^2}$$

- We may think of a rubber ball, with air inside. Let ψ be the radial displacement of the ball from the rest spherical position.
- For small displacements and a short period of time, the spherical wave equation is a reasonable model for the motion of the surface of the ball.
- However it is linear, so is a bad approximation for large displacements, and there is no damping term so the motion will continue for ever.
- Particular solutions are called **spherical harmonics**.

Separation of variables.

- We wish to solve the spherical wave equation

$$\frac{\partial^2 \psi}{\partial t^2} - \Delta_{\text{sph}} \psi = 0 \quad \text{for} \quad \psi = \psi(t, \theta, \phi)$$

- We can totally separate the spherical wave equation. However we shall separate t first, then (θ, ϕ) .
- Thus let $\psi(t, \theta, \phi) = T(t) \Upsilon(\theta, \phi)$.
- Show this gives

$$\frac{d^2 T}{dt^2} + \omega^2 T = 0 \quad \text{and} \quad \Delta_{\text{sph}} \Upsilon + \omega^2 \Upsilon = 0$$

where $-\omega^2$ is the constant of separation.

- The T equation is therefore solved for fixed frequency by setting

$$T(t) = A_\omega \cos(\omega t) + B_\omega \sin(\omega t)$$

The spherical equation

- For $\Upsilon = \Upsilon(\theta, \phi)$ we have

$$\Delta_{\text{sph}} \Upsilon + \omega^2 \Upsilon = 0$$

- We set $\omega^2 = n(n+1)$. (We see why later.)
- We shall see that the solutions to the spherical equation require that n is an integer. **What are the frequencies?**
- Thus we have

$$\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Upsilon}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 \Upsilon}{\partial \phi^2} + n(n+1) \Upsilon = 0$$

- We again use separation of variables, and set $\Upsilon(\theta, \phi) = \Theta(\theta)\Phi(\phi)$.
Show this gives

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left(n(n+1) - \frac{m^2}{\sin^2 \theta} \right) \Theta = 0$$

and

$$\frac{d^2 \Phi}{d\phi^2} + m^2 \Phi = 0$$

The $\Phi(\phi)$ equation



$$\frac{d^2\Phi}{d\phi^2} + m^2\Phi = 0$$

This is clearly simple harmonic oscillator.

- However the boundary condition are now periodic. Since ϕ is an angle. Thus $\Phi(\phi) = \Phi(\phi + 2\pi)$.
- We use the complex periodic functions. Thus we set

$$\Phi(\phi) = e^{im\phi}$$

- For this to be periodic, we require that $m \in \mathbb{Z}$.
- For real solutions of the wave equation we must take the real component

$$\psi(t, \theta, \phi) = \text{Re}(T(t)\Theta(\theta)\Phi(\phi))$$

The associated Legendre equation

- $$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left(n(n+1) - \frac{m^2}{\sin^2 \theta} \right) \Theta = 0$$

- We substitute in $z = \cos \theta$, which coincidental it corresponds to the z coordinated. We set

$$P(z) = P(\cos \theta) = \Theta(\theta)$$

Thus differentiating both sides by θ gives

$$-\sin \theta \frac{dP}{dz}(\cos \theta) = \frac{d\Theta}{d\theta}$$

Thus

$$-\sin^2 \theta \frac{dP}{dz}(\cos \theta) = \sin \theta \frac{d\Theta}{d\theta}$$

- Differentiating again by θ gives

$$\sin \theta \frac{d}{dz} \left(\sin^2 \theta \frac{dP}{dz}(\cos \theta) \right) = \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right)$$

The associated Legendre equation

- Hence

$$\frac{d}{dz} \left(\sin^2 \theta \frac{dP}{dz}(\cos \theta) \right) = \frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right)$$

- Substituting this into our original Θ equation

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d\Theta}{d\theta} \right) + \left(n(n+1) - \frac{m^2}{\sin^2 \theta} \right) \Theta = 0$$

we have

$$\frac{d}{dz} \left(\sin^2 \theta \frac{dP}{dz}(\cos \theta) \right) + \left(n(n+1) - \frac{m^2}{\sin^2 \theta} \right) P = 0$$

- Since $z = \cos \theta$ and $\sin^2 \theta = 1 - \cos^2 \theta = 1 - z^2$. Thus

$$\frac{d}{dz} \left((1 - z^2) \frac{dP}{dz} \right) + \left(n(n+1) - \frac{m^2}{1 - z^2} \right) P = 0$$

This is the **Associated Legendre Equation**.

The associated Legendre polynomials.

- Since P clearly depends on n and m as well as z we write $P_n^m(z)$. Thus we have the associated Legendre equation

$$\frac{d}{dz} \left((1 - z^2) \frac{dP_n^m}{dz} \right) + \left(n(n+1) - \frac{m^2}{1 - z^2} \right) P_n^m = 0$$

- The associated Legendre equation is a second order linear ODE. Therefore there are two solutions.
- If

$$n \in \{0, 1, 2, 3, \dots\} \quad \text{and} \quad m = -n, -n + 1, \dots, n - 1, n$$

then there is one solution which is bounded. This is the **associated Legendre polynomial**.

$$P_n^m(z) = \frac{1}{2^n n!} (1 - z^2)^{m/2} \frac{d^{n+m}}{dz^{n+m}} (z^2 - 1)^n.$$

- If n, m are not in these ranges then there is no bounded solution.
- The constant $1/2^n n!$ is simply convention.
- Observe that if m is odd then P_n^m is not a polynomial, but the name has stuck.

Spherical harmonics summary

- Up to ± 1 the spherical harmonics are therefore given by

$$Y_n^m(\theta, \phi) = \left(\frac{2n+1}{4\pi} \frac{(n-m)!}{(n+m)!} \right)^{1/2} e^{im\phi} P_n^m(\cos \theta)$$

where

$$P_n^m(z) = \frac{1}{2^n n!} (1-z^2)^{m/2} \frac{d^{n+m}}{dz^{n+m}} (z^2-1)^n.$$

- The solution to the wave equation for $\psi = \psi(t, \theta, \phi)$

$$\frac{\partial^2 \psi}{\partial t^2} - \Delta_{\text{sph}} \psi = 0$$

is given by

$$\psi = \sum_{n=0}^{\infty} \sum_{m=-n}^n \left(A_{nm} \cos(\sqrt{n(n+1)}t) + B_{nm} \sin(\sqrt{n(n+1)}t) \right) Y_n^m(\theta, \phi)$$

Some spherical harmonics

$$Y_0^0(\theta, \phi) = \frac{1}{2} \sqrt{\frac{1}{\pi}}$$

$$Y_1^{-1}(\theta, \phi) = \frac{1}{2} \sqrt{\frac{3}{2\pi}} e^{-i\phi} \sin \theta$$

$$Y_1^0(\theta, \phi) = \frac{1}{2} \sqrt{\frac{3}{\pi}} \cos \theta$$

$$Y_1^1(\theta, \phi) = \frac{-1}{2} \sqrt{\frac{3}{2\pi}} e^{i\phi} \sin \theta$$

$$Y_2^{-2}(\theta, \phi) = \frac{1}{4} \sqrt{\frac{15}{2\pi}} e^{-2i\phi} \sin^2 \theta$$

$$Y_2^{-1}(\theta, \phi) = \frac{1}{2} \sqrt{\frac{15}{2\pi}} e^{-i\phi} \sin \theta \cos \theta$$

$$Y_2^0(\theta, \phi) = \frac{1}{4} \sqrt{\frac{5}{\pi}} (3 \cos^2 \theta - 1)$$

$$Y_2^1(\theta, \phi) = \frac{-1}{2} \sqrt{\frac{15}{2\pi}} e^{i\phi} \sin \theta \cos \theta$$

$$Y_2^2(\theta, \phi) = \frac{1}{4} \sqrt{\frac{15}{2\pi}} e^{2i\phi} \sin^2 \theta$$

Eigen properties of spherical harmonics

- By construction the spherical harmonics $Y_n^m(\theta, \phi)$ are eigenfunctions of the spherical Laplacian

$$\Delta_{\text{sph}} Y_n^m = -n(n+1)Y_n^m$$

- Also since

$$Y_n^m = (-1)^m \left(\frac{2n+1}{4\pi} \frac{(n-m)!}{(n+m)!} \right)^{1/2} e^{im\phi} P_n^m(\cos\theta)$$

we see that

$$\frac{\partial}{\partial \phi} Y_n^m = im Y_n^m$$

- Thus the spherical harmonics $Y_n^m(\theta, \phi)$ are simultaneously eigenfunctions of two linear operators.
- A particular spherical harmonic $Y_n^m(\theta, \phi)$ is determined by the numbers n and m . This is equivalent to stating the eigenvalues of the operators Δ_{sph} and $\frac{\partial}{\partial \phi}$.
- Since the spherical harmonics simultaneously “diagonalise” the operators Δ_{sph} and $\frac{\partial}{\partial \phi}$. This implies that these two operators must commute.

Inner product on spherical functions

- A general complex valued function on the sphere is written $f : S^2 \rightarrow \mathbb{C}$. This means, in spherical coordinates (θ, ϕ) we can write $f = f(\theta, \phi)$ where $f(\theta, \phi) \in \mathbb{C}$.
- There is a natural inner product on functions on the sphere. Given two complex valued functions $f, g : S^2 \rightarrow \mathbb{C}$ on the sphere. We define the inner product of the functions f and g as

$$\langle f, g \rangle = \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \overline{f(\theta, \phi)} g(\theta, \phi) \sin \theta d\theta d\phi$$

- With respect to this inner product the spherical harmonics are orthonormal. That is

$$\langle Y_n^m, Y_{n'}^{m'} \rangle = \delta_{nn'} \delta_{mm'}$$

Completeness properties of spherical harmonics

- Any continuous complex spherical function $f : S^2 \rightarrow \mathbb{C}$ can be expanded into a series

$$f = \sum_{n=0}^{\infty} \sum_{m=-n}^n a_{nm} Y_n^m \quad \text{i.e.} \quad f(\theta, \phi) = \sum_{n=0}^{\infty} \sum_{m=-n}^n a_{nm} Y_n^m(\theta, \phi)$$

- From orthogonality we have

$$\langle Y_{n'}^{m'}, f \rangle = a_{n'm'} \quad \text{Why?}$$

Hence

$$f = \sum_{n=0}^{\infty} \sum_{m=-n}^n \langle Y_n^m, f \rangle Y_n^m$$

- We use this property to calculate the coefficients A_{nm} and B_{nm} for the general solution to the wave equation from the initial conditions $\psi(0, \theta, \phi)$ and $\dot{\psi}(0, \theta, \phi)$.

Laplace's equation for spherical symmetric space

- We can now solve Laplace's equation for $\psi(r, \theta, \phi)$

$$\Delta\psi = 0$$

for spherical symmetric situations.

- There are two scenarios we can consider.
 - All of \mathbb{R}^3 space with the origin, $r = 0$, removed. This is because we put a point source at the origin.
The Laplace's equation gives the gravitational potential for a point mass.
The Laplace's equation also gives the electrostatic potential a monopole, dipole, etc.
We therefore consider solutions where ψ is bounded for large r but is allowed to go infinite for small r .
 - Laplace's equation for a ball.
This corresponds to the gravitational potential, inside a massive shell.
Here we require that $\psi(r, \theta, \phi)$ is bounded at the origin, $r = 0$.

Laplace's equation for spherical symmetric space

- Recall that Laplace's equation $\Delta\psi$ for $\psi = \psi(r, \theta, \phi)$ is given by

$$\Delta\psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial\psi}{\partial\theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2\psi}{\partial\phi^2} = 0$$

- We can rewrite this as

$$\Delta\psi = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial\psi}{\partial r} \right) + \frac{1}{r^2} \Delta_{\text{sph}}\psi = 0$$

- And $\Delta_{\text{sph}}Y_n^m = -n(n+1)Y_n^m$ where $Y_n^m(\theta, \phi)$ is the spherical harmonic.
- Use separation of variables. Set $\psi(r, \theta, \phi) = R(r)\Upsilon(\theta, \phi)$. Hence the radial equation is given by

$$\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = n(n+1)R$$

where $n = 0, 1, 2, \dots$ **Show**

The radial equation



$$\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) = n(n+1)R$$

- We substitute in the ansatz $R(r) = r^\alpha$. **Show this implies**

$$\alpha(\alpha + 1) = n(n + 1)$$

- This can be satisfied by setting

$$\alpha = n \quad \text{and} \quad \alpha = -n - 1$$

- The solution to Laplace's equation $\Delta\psi = 0$ in spherical coordinates is

$$\psi = \sum_{n=0}^{\infty} \sum_{m=-n}^n \left(A_{nm} r^n + B_{nm} r^{-n-1} \right) Y_n^m(\theta, \phi)$$

Monopoles and dipoles

- Let us consider solutions where ψ is bounded as $r \rightarrow \infty$. Thus $A_{nm} = 0$ and

$$\sum_{n=0}^{\infty} \sum_{m=-n}^n B_{nm} r^{-n-1} Y_n^m(\theta, \phi)$$

- Thus the first few terms are

$$\begin{aligned} \psi = & \frac{B_{0,0}}{r} + \frac{1}{r^2} \left(B_{1,-1} Y_1^{-1} + B_{1,0} Y_1^0 + B_{1,1} Y_1^1 \right) \\ & + \frac{1}{r^3} \left(B_{2,-2} Y_2^{-2} + B_{2,-1} Y_2^{-1} + B_{2,0} Y_2^0 + B_{2,1} Y_2^1 + B_{2,2} Y_2^2 \right) \end{aligned}$$

- The first term is due to a monopole. This is spherically symmetric.
- The next three terms are due to simple dipoles. Any possible direction dipole can be constructed by setting $B_{1,-1}, B_{1,0}, B_{1,1}$. Observe these fall off quicker. Therefore dipoles are weaker than monopoles for large distances.
- The next five terms are due to a quadrupole. These fall off even quicker $1/r^3$.

Inside a ball

- Let us here consider only solutions which are bounded at $r = 0$. Hence all the $B_{nm} = 0$ and

$$\psi = \sum_{n=0}^{\infty} \sum_{m=-n}^n A_{nm} r^n Y_n^m(\theta, \phi)$$

- The first few terms are

$$\begin{aligned} \psi = & A_{0,0} + r \left(A_{1,-1} Y_1^{-1} + A_{1,0} Y_1^0 + A_{1,1} Y_1^1 \right) \\ & + r^2 \left(A_{2,-2} Y_2^{-2} + A_{2,-1} Y_2^{-1} + A_{2,0} Y_2^0 + A_{2,1} Y_2^1 + A_{2,2} Y_2^2 \right) \end{aligned}$$

- The first term gives us the spherically symmetric potential inside a ball. This is a constant potential.
- The next terms give us non a symmetric potential.